NO MOTION IN THE ROBOT.

MOTOR DOES NOT TURNS ON

AFTER REACHING THE END THE ROBOT STOPS ARE RELEASES THE LOAD.

ROBOT MOVES FORWARD USING ROBOTIC ARMS AND CARRYING THE LOAD.

ROBOTIC ARMS OF THE ROBOT CONNECTED TO THE PULLEYS COME IN MOTION.

PULLEYS CONNECTED TO MOTOR STARTS ROTATING.

**SERVO ON**

**SERVO OFF**

ULTRASONIC SENSOR SENSES THE ROPE AND THE BARRIERS IF PRESENT